# ON THE VARIA TIONAL METHOD OF DERIVATION OF EQUATIONS OF STATE FOR A MA TERIAL MEDIUM AND A GRAVITA TIONAL FIELD 

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#### Abstract

The formulation of equations of state for a continuous medium and gravitational field is considered in the framework of the general theory of relativity, using the fundamental variational equation. The arbitrarines of determination of equations of state is examined in detail, and problems of determining the energy-momentum tensor for the medium and gravitational field are clarified in the case of invariant dynamic and generally physical muler's equations. Obtained formulas and deductions are specifically defined for the gravitational field in vacuum. The developed theories make possible a proper evaluation of the essence of the various assumptions prevailing in the theory of the energymomentum pseudotensor and in the general problem of the possible form of equations of state for physical models.


1. Thevariationalequation, Let us consider the four-dimensonal pseudo-Riemannian space of events with metric signature (,,,---+ ) in the observer's coordinate syatem with variabies $x^{i}(i=1,2,3,4)$ and in the coordinate system with variables $\xi^{i}$ moving with the continuous medium in the space of events. The dynamic equations and the equations of state for the gravitational field and the medium are obtained within the frame-work of the general theory of relativity using the variational equation of the form

$$
\begin{equation*}
\delta \int_{V_{4}} \Lambda d \tau+\delta W=0 \tag{1.1}
\end{equation*}
$$

where $V_{4}$ is an arbitrary four-dimensional volume of the event space; $d \tau$ is an invariant element of volume $V_{4}$, and $\delta W$ is a functional defined below by the Lagrangian $\Lambda$

$$
\begin{equation*}
\Lambda=\Lambda\left(g_{i j}, \Gamma_{i j}{ }^{k}, \partial_{s} \Gamma_{i j}, x_{j}^{i}, \mu^{A}, \nabla_{i} \mu^{A}, K^{\wedge C}\right) \tag{1,2}
\end{equation*}
$$

where $x_{j}^{i}=\partial x^{i} / \partial \xi_{j}^{j}$ (functions $x^{i}=x^{i}\left(\xi^{j}\right)$ define the law of motion of the medium); $\mu^{A}$ are tensor components specified in the observer's coordinate system that define various physical fields or physical properties of the medium; $\nabla_{t}$ is the symbol of the covariant derivative defined in the observer's coordinate system $\partial_{i}=$ $\partial / \partial x^{i}$ are symbols of partial derivatives with respect to variables $x^{i} ; K^{\wedge C}$ are the nonvaried tensor components specified in the related coordinate system; $g_{i j}$ are contravariant components of the event space tensor in the observer's coordinate system, and $\Gamma_{i j}{ }^{k}$ are Christoffel symbols

$$
\Gamma_{i j}^{k}=1 / 2 g^{k s}\left(-\partial_{s} g_{i j}+\partial_{i} g_{s j}+\partial_{j} g_{s i}\right)
$$

If irreversible processes are taken into consideration and, also, when the coordinate system is subjected to extemal effects, a certain, generally nonholonomic, functional $\delta W^{*}$ is included in the variational equation (1.1) [2-4]. The theory developed below is based on the assumption that $8 W^{*}=0$.

Let us determine the system of subsequently used variations of determining parameters. We denote the arbitrary function $\eta^{A}\left(x^{i}\right)$ in the varied state by $\eta^{\prime A}$ ( $x^{i}$ ) . Assuming that $\eta^{\prime A}\left(x^{i}\right)$ differs only slightly from $\eta^{A}\left(x^{i}\right)$, the form of variation of function $\partial \eta^{A}$ is defined within first order smalls by the equality

$$
\begin{equation*}
\partial \eta^{A}=\eta^{A}\left(x^{i}\right)-\eta^{A}\left(x^{i}\right) \tag{1.3}
\end{equation*}
$$

It will be readily seen that the definition (1,3) implies that

$$
\partial \partial_{i} \eta^{A}=\partial_{i} \eta^{\prime A}-\partial_{i} \eta^{A}=\partial_{i} \partial \eta^{A}
$$

Besides the variation $\partial \eta^{A}$ we define the variation $\delta \eta^{A}$

$$
\begin{equation*}
\delta \eta^{A}=\partial \eta^{A}+\delta x^{i} \nabla_{i} \eta^{A}, \quad \delta x^{i}=x^{\prime i}\left(\xi^{j}\right)-x^{i}\left(\xi^{j}\right) \tag{1.4}
\end{equation*}
$$

where $\delta x^{i}$ are variations of the law of motion of the medium and are components of the four-dimensional vector,

The above definitions imply that if parameters $\eta^{A}$ are tensor components, then variation $\partial \eta^{A}$ and $\delta \eta^{A}$ are also tensor components of the same rank as $\eta^{A}$.

Using the definition of variation $\partial$, for the quantity $x_{j}{ }^{i}$ and the Christoffel symbols we can obtain [1]

$$
\begin{aligned}
& \partial x_{j}^{i}=-\delta x^{s} \nabla_{s} x_{j}^{1}+x_{j} \nabla_{s} \delta x^{i} \\
& \partial \Gamma_{i j}^{k}=1 / 2 g^{k s}\left(-\nabla_{s} \partial g_{i j}+\nabla_{i} \partial g_{s j}+\nabla_{j} \partial g_{s i}\right)= \\
& \quad 1 / 2\left[-g^{k s} \delta_{i}^{n} \delta_{j}^{q}+g^{k n}\left(\delta_{i}^{i} \delta_{j}^{q}+\delta_{j}^{s} \delta_{i}^{q}\right)\right] \nabla_{s} \partial g_{n q}
\end{aligned}
$$

For components $K \wedge C$ we have $8 K^{\wedge C}=0$, and for the variation of a volume element we have the formula

$$
\delta d \tau=\left(\nabla_{i} \delta x^{i}+1 / 2 g^{i j} \partial g_{i j}\right) d \tau
$$

We also determine for functions $\eta^{A}$ the variations $\delta^{\prime}$

$$
\begin{equation*}
\delta^{\prime} \eta^{A}=\partial \eta^{A}+\delta x^{i} \partial_{i} \eta^{A} \tag{1.5}
\end{equation*}
$$

If $\eta^{A}$ are tensor components, the covariant derivative for $\eta^{\boldsymbol{A}}$ can be defined by an equality of the form

$$
\begin{equation*}
\nabla_{i} \eta^{A}=\partial_{i} \eta^{A}+F_{B S}^{A j} \Gamma_{i j} \eta^{B} \tag{1.6}
\end{equation*}
$$

in which coefficients $F_{B z}^{A_{j}}$ represent the sum of various products of Kronecker symbols. Using coefficients $F_{B 8}^{A j}$ the variation $\delta^{\prime}$ of tensor components $\eta^{A}$ can be expressed in terms of variation $\delta$

$$
\delta^{\prime} \eta^{A}=\delta \eta^{A}+\delta x^{i}\left(-\nabla_{i} \eta^{A}+\partial_{i} \eta^{A}\right)=\delta \eta^{A}-F_{B j}^{A j} \Gamma_{i j}^{*} \eta^{B} \delta x^{i}
$$

## 2. The Eulerequationsandthefunctional 8 W.

 Variational of the action integral can be represented in the form$$
\begin{align*}
& \delta \int_{V_{i}} \Lambda d \tau=\int_{V_{i}}\left(\theta^{i j} \partial g_{i j}+M_{A} \partial \mu^{A}+F_{i} \delta x^{\dagger}\right) d \tau-  \tag{2,1}\\
& \int_{V_{i}} \nabla_{k}\left(P_{i}^{k} \delta x^{i}+M_{A}^{k} \delta \mu^{A}+T^{k i j} \delta g_{i j}+T^{k z i} \nabla_{\Delta} \delta g_{i j}\right) d \tau
\end{align*}
$$

where the following notation is used:

$$
\begin{aligned}
& \theta^{i j}=\frac{1}{2}\left\{\Lambda g^{i j}+2 \frac{\partial \Lambda}{\partial g_{i j}}+\nabla_{s}\left[g^{i k}\left(\frac{\delta \Lambda}{\delta \Gamma_{i j}{ }^{k}}-\frac{\partial \Lambda}{\partial \partial_{n} \Gamma_{i j}{ }^{k}} \Gamma_{n m}^{m}\right)-\right.\right. \\
& \left.\left.g^{i k}\left(\frac{\Delta \Lambda}{\partial \Gamma_{v j}{ }^{k}}-\frac{\partial \Lambda}{\partial \partial_{n} \Gamma_{i j}{ }^{k}} \Gamma_{n i n}^{m}\right)-g^{j k}\left(\frac{\partial \Lambda}{\partial \Gamma_{n j}^{k}}-\frac{\partial \Lambda}{\partial \partial_{n} \Gamma_{n i}^{k}} \Gamma_{n m}^{m}\right)\right]\right\} \\
& T^{k u i j}=-\frac{1}{2}\left(-g^{m} \frac{\partial \Lambda}{\partial \partial_{k} \Gamma_{i j}^{n}}+g^{i n} \frac{\partial \Lambda}{\partial \partial_{k} \Gamma_{s j}^{n}}+g^{n j} \frac{\partial \Lambda}{\partial \partial_{k} \Gamma_{s i}^{n}}\right)+N^{k u j} \\
& T^{k i j}=\frac{1}{2}\left[g^{n k}\left(\frac{\delta \Lambda}{\delta \Gamma_{i j}{ }^{n}}-\frac{\partial \Lambda}{\partial \partial_{q} \Gamma_{i j}{ }^{n}} \Gamma_{q m}^{m}\right)-\right. \\
& g^{i n}\left(\frac{8 \Lambda}{\delta \Gamma_{k j}^{m}}-\frac{\partial \Lambda}{\partial \partial_{q} \Gamma_{k j}^{n}} \Gamma_{q m}^{m}\right)- \\
& \left.g^{j n}\left(\frac{\Delta \Lambda}{\delta \Gamma_{k i}^{n}}-\frac{\partial \Lambda}{\partial \partial_{q} \Gamma_{k i}^{n}} \Gamma_{q m}^{m}\right)\right]+\nabla_{z} N^{k t j} \\
& P_{i}{ }^{k}=-\frac{\partial \Lambda}{\partial x_{j}{ }^{i}} x_{j}^{k}+\frac{\partial \Lambda}{\partial \nabla_{z} \mu^{A}} \nabla_{i} \mu^{A}-\Lambda \delta_{i}{ }^{k} \\
& F_{i}=-\frac{\partial \Lambda}{\partial x_{j}^{3}} \nabla_{i} x_{j}^{3}-\nabla_{B}\left(x_{j}^{3} \frac{\partial \Lambda}{\partial x_{j}^{i}}\right)-\frac{\partial \Lambda}{\partial K^{\wedge C}} \nabla_{i} K^{\wedge C} \\
& M_{A}=\frac{\partial \Lambda}{\partial \mu^{A}}-\nabla_{i} \frac{\partial \Lambda}{\partial \nabla_{i} \mu^{A}}, \quad M_{A}{ }^{k}=-\frac{\partial \Lambda}{\partial \nabla_{k} \mu^{A}} \\
& \frac{\delta \Lambda}{\delta \Gamma_{i j}{ }^{k}}=\frac{\partial \Lambda}{\partial \Gamma_{i j}{ }^{k}}-\partial_{s} \frac{\partial \Lambda}{\partial \partial_{s} \Gamma_{i j}{ }^{k}}+\frac{\partial \Lambda}{\partial \nabla_{s} \mu^{A}} \frac{\partial \nabla_{s} \mu^{A}}{\partial \Gamma_{i j}{ }^{k}}
\end{aligned}
$$

In formulas (2.2) the quantities $N^{k s i j}=-N^{* k i j}$ are arbitrary differentiable functions of any arguments and $\delta / \delta \Gamma_{i j}{ }^{k}$ denotes the variational derivalive. Quantities $\theta^{i j}, T^{k i j}$, and $T^{k s i j}$ are by definition symmetric with respect to indices $i$ and $j$

$$
\theta^{i j}=\theta^{i i}, T^{k i j}=T^{k j i}, T^{k s i j}=T^{k a j i}
$$

Taking into account formula (2.1) for variations of the action integral we obtain from the variational equation (1.1) the system of Buler's equations and the functional $\delta W$

$$
\begin{align*}
& \theta^{i j}=0, F_{i}=0, M_{A}=0  \tag{2.3}\\
& 8 W=\int_{\Sigma}\left(P_{i}^{k} \delta x^{i}+M_{A}^{k} \delta \mu^{A}+T^{k+j} \delta g_{i j}+T^{k \&(j} \nabla_{s} \delta g_{d j}\right) n_{k} d \sigma \tag{2,4}
\end{align*}
$$

where $n_{k}$ are components of the unit vector of the external normal to the three-dimensional surface $\Sigma$ that bounds volume $V_{4}$ and $d \sigma$ is an invariant element of surface $\Sigma$ 。

In classical theories (such as of perfect fluid, of elastic body, and of electromagnetic field) the equations that determine the terms of the integrand in 8 W are equations of state. The quantities $\boldsymbol{P}_{\boldsymbol{i}}{ }^{k}$ which appear in $\delta W$ and are defined by formula (2.2) are similar to components of the energy-momentum tensor in the special theory of relativity. Quantities of that type were used in $[1,4-6]$ in the context of the general theory of relativity. If the Lagrangian $\Lambda$ is a four-dimensional scalar, the quantities $P_{i}{ }^{k}$ are components of a second rank tensor, but in the general case when $\Lambda$ is not a scalar, $P_{i}{ }^{k}$ do not define any tensom.

Definitions (2,2) show that when Euler's equations (2.3) are invariant, the quantities $T^{k i j}$ and $T^{k s i j}$ in $\delta W$ are determined by the variational equation with some arbitrariness, owing to the presence. of the arbitrary function $N$. The definitions (2.2) of quantities $P$ and $T$ in the case of invariable buler's equations can also be varied by supplementing the Lagrangian $\Lambda$ by the divergent terms of the form $\nabla_{i} \Omega^{i}$, where $\Omega^{i}$ are specified in the form of functions that define the medium and field parameters. Thus, if Euler's equations and the functional 8 W expressed in the form (2.3) and (2.4), respectively, correspond to the Lagrangian $\Lambda$, then the same Euler's equations $(2,3)$ and functional $\delta W$ of the form

$$
\begin{aligned}
& \delta W=\int_{\frac{2}{}}\left(P_{i}^{\prime k} \delta x^{i}+M_{A}^{k} \delta \mu^{A}+T^{k M i j} \delta g_{i j}+T^{k j i} \nabla_{\delta} \delta g_{i j}-\delta \Omega^{k}\right) n_{k} d \sigma \\
& T^{\prime k i j}=T^{k i j}-1 / 2 \Omega^{k} g^{i j}, \quad P_{i}^{\prime k}=P_{i}^{k}+\nabla_{i} \Omega^{k}-\delta_{i} \nabla_{j} \Omega^{j}
\end{aligned}
$$

correspond to Lagrangian $\Lambda+\nabla_{i} \Omega^{i}$. In these equations $P_{i}{ }^{\prime k}$ are defined in conformity with [5].

The form of terms of the integrand in $8 W$ subetantially depends also on variations of determining parameters in $\delta W$. The use of a particular system of variations in $\delta W$ is, generally, a matter of convention, and is related to considerations of convenience and the posetbility of phyical interpretation of equations that define $\delta W$. The selection of variation $\delta$ defined by formula (1.4) in the exprestion for functional $\delta W$ of the form (2.4) is based on the following reasoning. First, when variations $\delta$ are used for scalar Lagrangians, the coefficients at variations are always
tensor components and, consequently are of an invariant geometric nature. Second, in the case of known classic models of media the variational equation (1.1) is the equation of energy when differentials along the world lines of points of the medium are substituted for $\delta$-variations, and the coefficients at variations $\delta W$ are defined by the usual equations of state. For real increments the transition of the basic variational equation (1.1) to the equation of energy can be used as the basis for establishing the expression for $\Lambda$ and in the general case fo that for $\delta W^{*}$.

It should be noted that the functional $\delta W$ as a whole remains unchanged when, owing to the presence of arbitrary functions $N$ or to the use of different variations of determining parameters, the definition of terms of that functional varies. However, when passing from Lagrangian $\Lambda$ to Lagrangian $\Lambda+\nabla_{i} \Omega^{i}$ the entire functional $\delta W$ is changed.
3. Invariant properties of the variational equation. Euler's equations (2.3) and formulas (2.4) for the functional $\delta W$ were obtained for an arbitrary dependence of the Lagrangian $\Lambda$ on arguments appearing in (1.2). Below we establish certain properties of Euler's equations and of the quantities $P_{i}{ }^{k}$ contained in $\delta W$ and related to the additional requirement for the Lagrangian $\Lambda$ to be a scalar.

Let us assume that the Lagrangian $\Lambda$ is a four-dimensional scalar and, consequently, invariant with respect to a group of arbitrary transformations of the observer's coordinate system, and calculate the variation of the action integral

$$
\delta_{G} \int \Lambda d \tau
$$

for the arbitrary (small) transformation $y^{i}=y^{i}\left(x^{j}\right)$ of variables $x^{i}$ of the observer's coordinate system. For this it is sufficient to set in formula (2.1) for the arbitrary variation of the action integral the variations $\delta x^{i}, \delta g_{i j}$ and $\delta \mu^{A}$ as follows:

$$
\begin{align*}
& \delta x^{i}=\delta \eta^{i}, \delta g_{i j}=-\nabla_{i} \delta \eta_{j}-\nabla_{j} \delta \eta_{i}  \tag{3.1}\\
& \delta \mu^{A}=F_{B i}^{A k} \mu^{B} \nabla_{k} \delta \eta^{i}
\end{align*}
$$

where within smalls of the first order $\delta \eta^{i}=y^{i}\left(x^{j}\right)-x^{i}$ and $\delta \eta_{j}=g_{t j} \delta \eta^{i}$ and the coefficients $F_{B i}^{A K}$ are the same as in formula (1.6) for the covariant derivative $\nabla_{i} \mu^{A}$. Subatituting expressions (3.1) into formula (2.1) for the arbitrary variation of the action integral we obtain

$$
\begin{align*}
& \delta_{G} \int_{V_{4}} \Lambda d \tau \equiv \int_{V_{4}}\left[2 \nabla_{k} \theta_{i}{ }^{k}+F_{i}-M_{A} \nabla_{i} \mu^{A}-\nabla_{k}\left(M_{A} F_{B i}^{A k} \mu^{B}\right)\right] \delta \eta^{i} d \tau-  \tag{3.2}\\
& \int_{V_{4}} \nabla_{k}\left[\left(2 \theta_{i}^{k}-M_{A} F_{B i}^{A k} \mu^{B}+P_{i}^{k}\right) \delta \eta^{i}+\right. \\
& \left.\quad\left(M_{A}^{k} F_{B i j^{B}}{ }^{B}-2 T_{. . i}^{k j}\right) \nabla_{j} \delta \eta^{i}-2 T^{k s i j} \nabla_{i} \nabla_{j} \delta \eta_{i}\right] d \tau
\end{align*}
$$

Since $\Lambda$ is assumed to be a scalar, we have

$$
\begin{equation*}
\delta_{G} \int_{V_{A}} \Lambda d \tau \equiv 0 \tag{3.3}
\end{equation*}
$$

Taking into account formula (3.2), for the variation of the action integral at coordinate transformetion with $\delta \eta^{i}$ equal zero on surface $\Sigma$, from $(3,3)$ we obtain the identity

$$
2 \nabla_{k} \theta_{i}^{k}+F_{i}-M_{A} \nabla_{i} \mu^{A}-\nabla_{k}\left(M_{A} F_{B i}^{A k} \mu^{B}\right)=0
$$

which is satisfied only owing to the scalar properties of Lagrangian $\Lambda$, independently of the fulfilment of Euler's equations. This identity aleo impliea that on the astumpthon that $\Lambda$ is a scalar the second of Equ. (2.3) (obtained with variations $\delta x^{i}$ ) is a corollary of the remaining Buler's equations.

Carrying out differentiation in the second integral of (3.2) and collecting terms containing variations $\delta \eta^{i}$ and their gradients, we obtain the following formula:

$$
\begin{aligned}
& \delta_{G} \int_{V_{4}} \Lambda d \tau=\int_{V_{4}}\left\{\left[F_{i}-M_{A} \nabla^{\prime} \mu^{A}-\nabla_{k} P_{i}^{k}-\frac{2}{3} T^{k o n j}\left(\nabla_{k} R_{m i j}+\nabla_{s} R_{k n i j}\right)+(3.4)\right.\right. \\
& \left.\left(-\frac{1}{2} M_{A}{ }^{*} P_{B q}^{A m} \mu^{B}+T_{\cdots, q}^{s m}+\nabla_{k} T^{k a m \cdot}\right) R_{\cdot i d m}^{q}\right] \delta \eta^{i}+ \\
& {\left[-2 \theta_{i}{ }^{k}+M_{A} F_{B i}^{A K} \mu^{B}-P_{i}{ }^{k}+\nabla_{\mathrm{q}}\left(-M_{A}{ }^{q} F_{B i}^{A \mu^{B}}+2 T_{i}^{\mathrm{q}}{ }_{i}\right)+\right.} \\
& \frac{1}{3} T_{\cdots \cdot i}^{q m n}\left(R_{\cdot m n q}^{k}-R_{\cdot q m n}^{k}\right)+\left(T^{j k n q}+T^{j n k q}+T^{k j n q}\right) R_{q i j n}+
\end{aligned}
$$

$$
\begin{aligned}
& \left.\nabla_{(k} \nabla_{m} \delta \eta^{i}+2 T^{k+j} \nabla_{\{k} \nabla_{s} \nabla_{i j} \delta \eta_{j}\right\} d \tau
\end{aligned}
$$

where the parentheses enclosing subscripts at tensor components denote symmertization relative to these subecripts, and $R_{\text {.tsj }}^{\boldsymbol{\pi}}$ are components of the curvature tensor of the preudo-Riemannian space of events.

Using formula (3.4) we obtain from condition (3.3) which defines scalar properties the system of identities

$$
\begin{align*}
& F_{i}-M_{A} \nabla_{i} \mu^{A}-\nabla_{k} P_{i}^{k}-{ }^{2} / \mathrm{s} T^{k m i j}\left(\nabla_{k} R_{m i j}+\nabla_{s} R_{k m i j}\right)+ \tag{3.5}
\end{align*}
$$

$$
\begin{aligned}
& -2 \theta_{i}^{k}+M_{A} F_{B i}^{A k} \mu^{B}-P_{i}^{k}+\nabla_{q}\left(-M_{A}^{q} F_{B i}^{A k} \mu^{B}+2 T_{i}^{q k}\right)+ \\
& { }_{1 / 3} T_{\cdots \cdot i}^{q m n}\left(R_{\cdot m n q}^{k}-R_{\cdot q m n}^{k}\right)+\left(T^{j k n q}+T^{j n k q}+T^{k j n q}\right) R_{q i j n}+ \\
& T_{\cdots \cdots i}^{j m n} R_{n m j}^{k} \equiv 0 \\
& -F_{B}^{A(m} M_{A}{ }^{k)} \mu^{B}+2 T^{(k m)} \cdot \underset{i}{ }+2 \nabla_{q} T^{q(k m)} \cdot{ }_{i} \equiv 0 \\
& T^{(k s i) j} \equiv 0
\end{aligned}
$$

Similar identities were considered in [7] in the case when components $T^{k s i)}$ are symmetric relative to superscripti $k$ and $s$, however, without taling into account the arbitrary function $N$.

The first of identities (3.5) shows that in virtue of Euler's equations (2.3) the components of tensor $P_{t}^{k}$ satisfy the equation

$$
\begin{align*}
& \nabla_{k} P_{i}^{k}=-2 / 3 T^{k e n j}\left(\nabla_{k} R_{s n i j}+\nabla_{s} R_{k n i j}\right)+  \tag{3.6}\\
& \quad\left(-1 / 2 M_{A}^{s} F_{B q}^{A m} \mu^{B}+T_{\cdot q}^{s m+}+\nabla_{k} T_{\cdots \cdot q}^{k s m \cdot}\right) R_{i s m}^{q}
\end{align*}
$$

while the second of these identities implies that in virtue of (2.3) components $P_{i}^{k}$ may be written as

$$
\begin{align*}
& P_{i}^{k}=\nabla_{q}\left(-M_{A}^{q} F_{B i}^{A k} \mu^{B}+2 T_{\cdot i}^{q k}\right)+1 / 3 T_{i}^{q m n}\left(R_{m n q}^{k}-R_{\cdot q m n}^{k}\right)+  \tag{3.7}\\
& \quad\left(T^{j k n q}+T^{j n k q}+T^{k j q}\right) R_{q i j n}+T_{\cdots, .}^{j m n} R_{\cdot n m j}^{k}
\end{align*}
$$

4. Pseudotensors ofenergy-momentum. Substituting in formula (2.4) which defines functional $\delta W$ the tensor variations $\delta^{\prime}$ (defined by equality (1.5)) for variations $\delta$, we obtain

$$
\begin{equation*}
\delta W=\int_{\Sigma}\left(t_{i}^{k} \delta x^{i}+t_{i}^{k s} \partial_{s} \delta x^{i}+\theta^{k j i j} \delta^{\prime} g_{i j}+T^{k s i j} \partial_{s} \delta^{\prime} g_{i j}+M_{A}{ }^{k} \delta^{\prime} \mu A\right) n_{k} d \sigma \tag{4,1}
\end{equation*}
$$

where $t_{i}{ }^{k}, t_{i}{ }^{k z}$, and $\theta^{k i j}$ are defined by

$$
\begin{align*}
& t_{i}^{k}=-\frac{\partial \Lambda}{\partial x_{j}{ }^{k}} x_{j}^{k}+\frac{\partial \Lambda}{\partial \nabla_{i} \mu^{A}} \partial_{i} \mu^{A}-\theta^{k n j} \partial_{i} g_{n j}-  \tag{4.2}\\
& \quad T^{k=m j} \partial_{i} \partial_{s} g_{n j}-\Lambda \delta_{i}^{k}+\frac{1}{\sqrt{-g}} \partial_{s}\left(N_{i}{ }^{k s} \sqrt{-g}\right), \quad g=\operatorname{det}\left\|g_{i j}\right\| \\
& t_{i}^{k z}=-T^{k m j \partial_{i} g_{n j}+N_{i}^{k z}} \\
& \theta^{k i j}=T^{k i j}-T^{k s m j} \Gamma_{s m}^{i}-T^{k s m i} \Gamma_{s m}^{j}
\end{align*}
$$

where $N_{i}{ }^{k s}=-N_{i}{ }^{{ }^{k}}$ are arbitrary differentiable functions, and $T^{k i j}$ and $T^{k s i j}$ are defined by equalities (2.2). Components $t_{i}{ }^{k}$ satisfy in virtue of Euler's equations the differential law of conservation

$$
\begin{equation*}
\partial_{k} \sqrt{-g} t_{i}^{k}=0 \tag{4.3}
\end{equation*}
$$

and are usually called components of the energy-momentum pseudotensor. It will be seen from (4.2) that components of the pseudotensor $\sqrt{-g} t_{i}{ }^{k}$ are determined by the variational equation with an accuracy within the term $\partial_{s}\left(N_{i}{ }^{k 8} \sqrt{-g}\right)$. Note that the law of conservation is here unrelated to the invariance of the Lagrangian. - Determination of the energy-momentum pseudotensor using the invariance properties of Lagrangian $\Lambda$ yields the same formula (4.2) with the same arbitrariness.
5. Transformation of functional $\delta W$. It is obvious that owing to the indicated arbitrariness of the definition of parameters $t, \theta$, and $T$ in $\delta W$ it is not posible to attribute to these any physical meaning without some further special assumptions. It is, however, possible to indicate an algorithm for a unique determination of terms in $8 W[3-5,8-12]$. The respective transformation related
to the decomposition of gradients $\nabla_{s}$ of variations that determine parameters in $\delta W$ in terms of components tangent and normal to surface $\Sigma$, is of the form

$$
\begin{equation*}
\nabla_{s}=\left(\delta_{s}{ }^{i}-e n_{s} n^{i}\right) \nabla_{i}+e n_{s} n^{i} \nabla_{i}=\zeta_{s}{ }^{\alpha} \nabla_{\alpha^{*}}{ }^{*}+e n_{s} D / D n \tag{5,1}
\end{equation*}
$$

where $D / D n=n^{i} \nabla_{i}$ is the covariant derivative with respect to the normal to surface $\Sigma ; \varepsilon=g_{i j} n^{i} n^{j}$ is the sign indicator of the normal vector modulus, and $\nabla_{\alpha}{ }^{*}$ is the covariant derivative on surface $\Sigma$ in the coordinate system with variables $u^{\alpha}$ ( $\alpha=1,2,3$ ). Cornponents $\zeta_{A}^{\alpha}$ in formula (5.1) are defined by the equality $\zeta_{B}^{\alpha}=$ $G^{\alpha \beta} g_{a i} \zeta_{\beta}^{i}$ in which $G^{\alpha \beta}$ are covariant components of the first metric tensor of surface $\Sigma$ in the system of coordinates $u^{\alpha}$, and $\zeta_{\beta}{ }^{i}=\partial x^{i} / \partial u^{\beta}$ are components of basis vectors tangent to $\Sigma$. To obtain the second part of formula (5, 1) it is also necessary to use the equality

$$
\delta_{s}^{j}-\varepsilon n_{s} n^{j}=\zeta_{a}^{\alpha \zeta_{a_{2}}^{j}}
$$

which links the normal vector components $n_{i}$ with components of vectors $\zeta_{=}{ }^{i}$ tangent to surface $\Sigma$.

In the case of reasonably smooth surfaces $\Sigma$ and admistible functions and their variations by substituting in formula (2.4) for $\delta W$ the expressions (5.1) for gradients $\nabla_{s}$. it is possible to tranaform the formula for $\delta W$ to the form

$$
\begin{equation*}
\delta W=\int_{2}\left(n_{k} P_{i}^{k} \delta x^{i}+n_{k} M_{A}^{*} \delta \mu^{A}+T_{(0)}^{i j} \delta g_{i j}+T_{(i)}^{i j} \frac{D}{D n} \delta g_{i j}\right) d \sigma \tag{5,2}
\end{equation*}
$$

where

$$
\begin{equation*}
T_{(1)}^{i j}=\varepsilon n_{k} n_{s} T^{k s i j}, \quad T_{(0)}^{i j}=n_{k} T^{k i j}-\nabla_{\alpha}^{*}\left(\zeta_{s} \alpha_{n_{k}} T^{k * i j}\right) \tag{5,3}
\end{equation*}
$$

Using the derived equations of the theory of surfaces [15]

$$
\nabla_{\alpha} \xi_{\beta^{*}}=b_{\alpha \beta} n^{*}, \quad \nabla_{\alpha}^{*} n_{k}=-\varepsilon b_{\alpha \beta} \zeta_{k}^{\beta}
$$

where $b_{\alpha \beta}$ are components of the second metric tensor of surface $\Sigma$; the expression for quantities $T_{(0)}^{i j}$ in (5.3) can, also, be written in the form

$$
\begin{aligned}
& T_{(0)}^{i j}=n_{k}\left(T^{k 4}-\nabla_{s} T^{k \alpha i j}+e n_{s} \frac{D}{D n} T^{k \alpha i j}\right)+ \\
& \quad T^{k \alpha t j}\left(8 b_{\alpha \beta \beta} \sigma_{k}^{\alpha} b_{k}^{\beta}-b_{\alpha}^{\alpha} n_{k} n_{s}\right), \quad b_{\alpha}^{\alpha}=G^{\alpha \beta} b_{\alpha \beta}
\end{aligned}
$$

The quantities $P_{i}{ }^{k} n_{k}, T_{(0)}^{(f)}$, and $T_{(i)}^{i j}$ in (5.2) are uniquely determined for a specified lagrangian $\Lambda$ by the variational equation and are independent of the abitrary functions $N$ (this can be checked drectly). Relationibip at discontiauities and boundary conditions that correspond to the selected Lagrangian are formulated [3,4, 8-12ך using the above quantities determined at discontimities and boundaries.

When $\Lambda=\Lambda\left(R, g_{i j}, \mu^{A}, \nabla_{k} \mu^{A}, x_{j}{ }^{i}, K^{\wedge} C^{C}\right)$ the formula of type (5.2) for $\delta W$ was derived by Sedov [4], and for $\delta W$ with noncovariant derivatives $\partial / \partial n=n_{n}^{i} \partial_{4}$ appeared
in $[10,11]$ and in $[3,9]$ in the context of the special theory of relativity.
6. Theclassicalgeneraltheory ofrelativity. Letus now apply the derived formulas to a gravitational field in vacuum when the Lagrangian $\Lambda$ is defined by

$$
\begin{equation*}
\Lambda=\frac{1}{2 x} R+\nabla_{i} \Omega^{i} \tag{6.1}
\end{equation*}
$$

where $R$ is the scalar curvature of the space of events, $x$ is the Einstein gravitational constant, and $\Omega^{i}$ are specified functions whose form will not be defined here (for possible definitions of functions $\Omega^{i}$ see [5]). In this case Euler's equations for the event space metric are expressed in terms of Einstein's equations

$$
R_{i j}-1 / 2 R g_{i j}=0
$$

where $R_{i j}=R_{\cdot i m j}^{m}$ are components of the Ricci tensor and the functional $\delta W$ is of the form

$$
\begin{equation*}
\delta W=\int_{\Sigma}\left(P_{i}^{k} \delta x^{i}+T^{k i j} \delta g_{i j}+T^{k \pi i j} \nabla_{s} \delta g_{i j}-\delta \Omega^{k}\right) n_{\kappa} d \sigma \tag{6.2}
\end{equation*}
$$

where

$$
\begin{align*}
& P_{i}^{k}=-\frac{1}{2 x} R \delta_{i}^{k}+\nabla_{i} \Omega^{k}-\delta_{i}^{k} \nabla_{j} \Omega^{j}  \tag{6.3}\\
& T^{k i j}=-1 / 2 \Omega^{k} g^{i j}+\nabla_{s} N^{k s i j} \\
& T^{k \varepsilon i j}=\frac{1}{2 x}\left[g^{i j} g^{k s}-1 / 2\left(g^{i t} g^{j k}+g^{j \varepsilon} g^{i k}\right)\right]+N^{k \pi i j}
\end{align*}
$$

Formala (6.2) for $\delta W$ is given in [1] for $\Omega^{i}=0$ and $N^{k o i j}=0$. Functions $\Omega^{i}$ were considered in [5].

Separating in (6.2) the derivatives with respect to the normal we can express 8 W in the form

$$
\delta W=\int_{2}\left(P_{i}^{k} n_{k} \delta x^{i}+T_{(0)}^{i j} \delta g_{i j}+T_{(1)}^{i j} \frac{D}{D n} \delta g_{i j}-n_{k} \delta \Omega^{k}\right) d \sigma
$$

where

$$
\begin{aligned}
& T_{(1)}^{i j}=\frac{1}{2 x}\left(g^{i j}-\varepsilon n^{i} n^{j}\right) \\
& T_{(0)}^{i j}=-\frac{1}{2} n_{k} \Omega^{k} g^{i j}+\frac{1}{2 x}\left(b_{\alpha}{ }^{\alpha} n^{i} n^{j}-\varepsilon b^{\alpha \beta} \zeta_{\alpha}^{i} \zeta_{\beta}^{j}\right)
\end{aligned}
$$

Using the noncovariant variations $\delta^{\prime} g_{i j}$ we obtain the following expresaion for $\delta W$ :

$$
\begin{equation*}
\delta W=\int_{\Sigma}\left(t_{i}{ }^{k} \delta x^{i}+t_{i}{ }^{k s} \partial_{s} \delta x^{i}+\theta^{k i j} \delta^{\prime} g_{i j}+T^{k \Omega i j} \partial_{s} \delta^{\prime} g_{i j}-\delta^{\prime} Q^{k}\right) n_{k} d \sigma \tag{6.4}
\end{equation*}
$$

where

$$
\begin{aligned}
& t_{i}{ }^{k}=\frac{1}{x}\left(R_{i}^{k}-\frac{1}{2} R \delta_{i}^{k}\right)+\frac{1}{\sqrt{-g}} \partial_{s} \times \\
& \quad\left\{\sqrt{-g}\left[\frac{1}{2 x}\left(g^{k m} g^{j s}-g^{k k} g^{s m}\right) \partial_{j} g_{i m}+\delta_{i}^{4} \Omega^{k}-\delta_{i}^{k} \Omega^{s}+N_{i}^{k s}\right]\right\} \\
& t_{i}^{k s}=\frac{1}{2 x}\left(g^{k i} g^{s m}-g^{k s} g^{m y}\right) \partial_{i} g_{m j}+N_{i}^{k s} \\
& \theta^{k i j}=\frac{1}{4 x}\left[\left(g^{k i} g^{n s}-g^{k s} g^{n i}\right) \Gamma_{s n}^{j}+\left(g^{k i} g^{n s}-g^{k s} g^{n j}\right) \Gamma_{n d}^{i}\right]- \\
& \quad \frac{1}{2} \Omega^{k} g^{i j}+\frac{1}{\sqrt{-g}} \partial_{s}\left(\sqrt{-g} N^{k s i j}\right)
\end{aligned}
$$

Components $T^{k u i j}$ in (6,4) are defined by the equality (6.3).
Since in virtue of Einstein's equations the mixed components of the paeudotensors of the gravitational field energy momentum, proposed by various authors, are represented in the form of antirymmetric components with three indices, hence it is poasble to obtain as $t_{i}{ }^{k}$ in (6.5) all of the proposed formulas for the energy-momentum pseudotensors with mixed indices even when $\Omega^{i}=0$ and $\delta \Omega^{i}=0$ merely by the choice of the arbitrary functions $N_{i}{ }^{k s}$. For example, function $N_{i}{ }^{k s}=0$ corresponds to the Lorentz pseudotensor, and for the Einstein pseudotensor we have

$$
\begin{gathered}
N_{i}^{k s}=\frac{1}{2 x}\left\{-\left(g^{k m} g^{j s}-g^{k j} g^{s m}\right) \partial_{g g_{i m}}-\right. \\
\left.\frac{1}{\sqrt{-g}} g_{i n} \partial_{m}\left[(-g)\left(g^{k n} g^{s m}-g^{s m} g^{k m}\right)\right]\right\}
\end{gathered}
$$

For $\Omega^{i} \neq 0$ the preceding results are also obtained by the overdetermination of $N_{i}{ }^{k}$. In particular, if in the Lagrangian ( 6,1 ) functions $\Omega^{i}$ are deftued by the equality

$$
\Omega^{i}=\frac{1}{2 x}\left(g^{s i} \Gamma_{s j}^{j}-g^{j s} \Gamma_{j s}^{i}\right)=\frac{1}{2 x(-g)} \partial_{s}\left[(-g) g^{s i}\right]
$$

the Lagrancian $\Lambda$ is independent of derivatives of Christoffel symbols, and formula $(6,2)$ for $\delta W$ becomes

$$
\begin{equation*}
\delta W=\int_{\Sigma}\left(t_{i}^{k} \delta x^{i}+N_{i}^{k z} \partial_{*} \delta x^{i}+\theta^{k i j} \delta^{\prime} g_{i j}+N^{k s i j} \partial_{n} \delta^{\prime} g_{i j}\right) n_{K} d \sigma \tag{6.6}
\end{equation*}
$$

where $N_{i}^{k s}=-N_{i}^{* k}$ and $N^{k s i j}=-N^{s k i j}$ are arbitrary, and for $t_{i}{ }^{k}$ and $\theta^{k i j}$ we have

$$
\begin{align*}
t_{i}^{k} & =\frac{1}{x}\left(R_{i}^{k}-\frac{1}{2} R{\theta_{i}^{k}}_{k}-\right.  \tag{6.7}\\
& \frac{1}{2 x} \partial_{s}\left\{\frac{1}{\sqrt{-g}} g_{i n} \partial_{m}\left[(-g)\left(g^{k n} g^{s m}-g^{s n} g^{k m}\right)\right]\right\}+ \\
& \frac{1}{\sqrt{-g}} \partial_{s}\left(N_{i}^{k s} \sqrt{-g}\right)
\end{align*}
$$

$$
\begin{aligned}
& \theta^{k i)}=\frac{1}{4 x}\left[\left(g^{i j} g^{s p}-g^{s i} g^{3 p}-g^{j s} g^{i p}\right) \Gamma_{s p}^{k}+\right. \\
& \left.\quad\left(-g^{i j} g^{s k}+g^{s i} g^{i k}+g^{j s} g^{i k}\right) \Gamma_{s p}^{p}\right]+\frac{1}{\sqrt{-g}} \partial_{s}\left(\sqrt{-g} N^{k s i j}\right)
\end{aligned}
$$

According to Einstein when $N_{i}{ }^{k s}=0$, components $t_{i}{ }^{k}$ in (6,7) are components of the pseudotensor of the gravitational field energy-momentum.

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